

### Structure

• Set Screw Type

**XGT** Standard type → P.xxxx **XGS** Short type → P.xxxx

High-gain rubber Hex socket set screw

• Single Clamping Type **XGT-CS** Standard type → P.xxxx **XGS-CS** Short type → P.xxxx



• Double Clamping Type

**XGT-C** Standard type → P.xxxx

**XGL-C** Long type → P.xxxx

**XGS-C**] Short type → P.xxxx



• XGT-C XGL-C XGS-C Split Type Easy to mount and remove screws.





The designed shape of vibration-absorbing rubber achieves high torsional stiffness and high torque according to the finite element method. This product also succeeds in elongating its life by evenly dispersing the stress focusing on around the inner diameter of the jaw throughout the entire jaw.

### Applicable motors

	XGT / XGL / XGS
Servomotor	0
Stepping Motor	•
General-purpose Motor	•

### ②: Excellent ●: Available

### Property

	XGT / XGL / XGS
Zero Backlash	0
For Servomotor High Gain	0
High Torque	0
High Torsional Stiffness	0
Allowable Misalignment	0
Vibration Absorption Characteristics	0
Allowable Operating Temperature	−20°C to 80°C

- O: Excellent O: Very good
- A completely integrated flexible coupling that connects hubs on both sides with high-gain rubber.
- It is suitable for control motors with high responsiveness, enabling high-accuracy positioning and shortened stabilization time.
- About reduction of stabilization time → P.xxxx
- Application

Actuator / Surface-mount machine / High precision XY stage / Index table

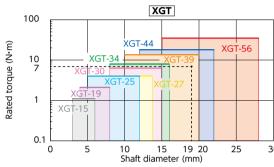
Material/Finish

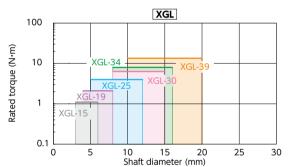
	TOI IS
	XGT / XGL / XGS
Hub	A2017
High-Gain Rubber	HNBR
Hex Socket Head Cap Screw / Hex Socket Set Screw	SCM435 Ferrosoferric Oxide Film (Black)

# Selection

# • Selection Based on Shaft Diameter and Rated

The area bounded by the shaft diameter and rated torque indicates the selection size.



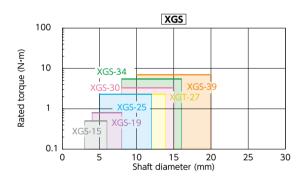






### Selection Example

In case of selected parameters of shaft diameter of  $\phi$ 19 and load torque of 7 N·m, the selected size is XGT-39C



## • Selection Based on the Rated Output of the Servomotor

Rated Output (W)	Servomotor Specifications*1	Selection Size				
	Diameter of Motor Shaft (mm)	Rated Torque (N·m)	Instantaneous Max. Torque (N·m)	XGT	XGL	xgs
10	5 - 6	0.032	0.096	15C	15C	15C
20	5 - 6	0.064	0.19	15C	15C	15C
30	5 - 7	0.096	0.29	19C	19C	19C
50	6 - 8	0.16	0.48	19C	19C	19C
100	8	0.32	0.95	19C	19C	25C
200	9 - 14	0.64	1.9	27C	30C	27C
400	14	1.3	3.8	27C	30C	34C
750	16 - 19	2.4	7.2	39C	39C	-

\*1: Motor specifications are based on general values. For details, see the motor manufacturer's catalogs. This is the size for cases where devices such as reduction gears are not used.

### Related Products

NBK.

XGT2 enables further improvement of productivity by adding damping performance to XGT .



• Part number specification



Please refer to dimensional table for part number specification.

Please combine with Stainless Steel Screw Alteration Service | Available / Add'l charge

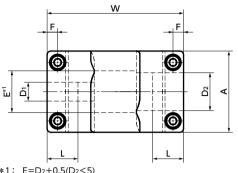
Available / Add'l charge

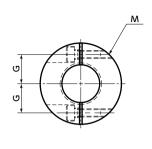


2 Zero Backlash Light gain supported High torque Vibration absorption

XGL-C







\*1: E=D<sub>2</sub>+0.5(D<sub>2</sub><5)  $E=D_2+1(D_2\geq 5)$ 

# Dimensions

Unit:mm

Part Number 1	А	L	w	F	G	M	Screw Tightening Torque (N·m)
XGL-15C	15	6.5	30	2.15	5	M1.6	0.25
XGL-19C	19	7.7	34	2.65	6.5	M2	0.5
XGL-25C	25	9.5	42	3.25	9	M2.5	1
XGL-30C	30	11	42	4	11	M3	1.5
XGL-34C	34	12	44	4	12.25	M3	1.5
XGL-39C	39	15.5	55	4.5	14.5	M4	2.5

Part Number	Standard Bo	Standard Bore Diameter D1-D2 2											
XGL-15C	3 - 5	5 - 5	5 - 6										
XGL-19C	4 - 5 6.35 - 8	5 - 5 8 - 8	5 - 6	5 - 7	5 - 8	6 - 6	6 - 6.35	6 - 8					
XGL-25C	5 - 8 10 - 10	6 - 8 10 - 12	6 - 10	6.35 - 8	8 - 8	8 - 10	8 - 11	8 - 12					
XGL-30C	8 - 8 10 - 14	8 - 10 11 - 12	8 - 11 12 - 14	8 - 12	8 - 14	8 - 15	10 - 10	10 - 11					
XGL-34C	8 - 8 14 - 15	8 - 10	8 - 12	8 - 14	10 - 11	10 - 14	11 - 12	12 - 14					
XGL-39C	10 - 10	10 - 12	10 - 14	12 - 14	14 - 15	15 - 19							

- All products are provided with hex socket head cap screw.
- Recommended tolerance for shaft diameters is h6 and h7.
- In case of mounting on D-cut shaft, be careful about the position of the D-cut surface of the shaft.
- $\bullet$  For the shaft insertion amount to the coupling, see Mounting/maintenance.

# Performance

Part Number	Max. Bore Diameter	Max Rore Diameter	Torque		Moment*2	Static Torsional Stiffness (N·m/rad)	Max. Lateral Misalignment (mm)	Max. Angular Misalignment (°)		Mass *2 (g)
XGL-15C	6	_	1.1	42000	3.3×10 <sup>-7</sup>	32	0.15	1.5	±0.2	11
XGL-19C	8	6	2.1	33000	9.7×10 <sup>-7</sup>	77	0.15	1.5	±0.2	19
XGL-25C	12	9	4	25000	3.5×10 <sup>-6</sup>	130	0.15	1.5	±0.2	38
XGL-30C	15	11	6.3	21000	7.3×10 <sup>-6</sup>	200	0.2	1.5	±0.3	53
XGL-34C	16	12	8	18000	1.3×10 <sup>-5</sup>	280	0.2	1.5	±0.3	73
XGL-39C	20	15	13.5	16000	2.8×10 <sup>-5</sup>	450	0.2	1.5	±0.3	117

\*1: Correction of rated torque due to load fluctuation is not required. If ambient temperature exceeds 30°C, be sure to correct the rated torque with temperature correction factor shown in the following table. The allowable operating temperature of  $\overline{\textbf{XGL-C}}$  is  $-20^{\circ}\text{C}$  to  $80^{\circ}\text{C}$ .

\*2: These are values with max. bore diameter.

• Ambient Temperature / Temperature Correction Factor

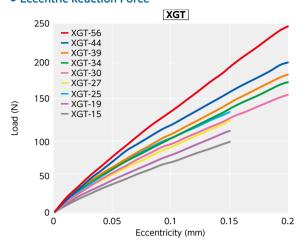
Ambient Temperature	<b>Temperature Correction Factor</b>
–20℃ to 30℃	1.00
30℃ to 40℃	0.80
40°C to 60°C	0.70
60℃ to 80℃	0.55

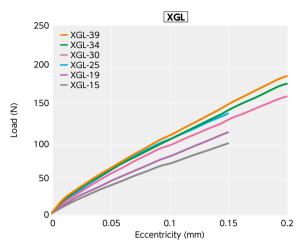
• Part number specification

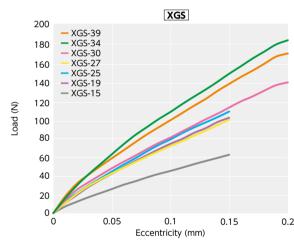


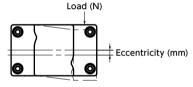
# Technical Information

#### Eccentric Reaction Force







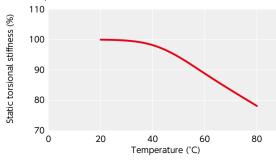


This is the force generated when placing **XGT XGL XGS** in an eccentric condition. As the eccentric reaction force becomes smaller, the force acting on the shaft bearing also becomes smaller.

# Change in static torsional stiffness due to temperature

This is a value under the condition where the static torsional stiffness at  $20^{\circ}$  is 100%.

Changes in the static torsion spring constant within the operating temperature are shown in the graph. Before using the unit, be aware of the deterioration of responsiveness.

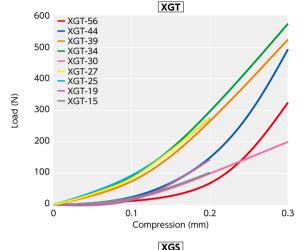


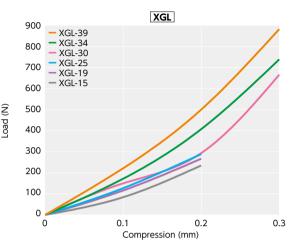
# Physical property and chemical resistance of highgain type rubber (HNBR)

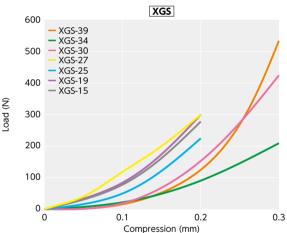
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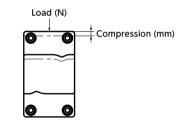
 $\odot$ : Excellent  $\odot$ : Available depending on conditions  $\times$ : Not available

#### • Thrust Reaction Force









This is the force generated when compressing **XGT XGL XGS** in the axial direction. As the thrust reaction force becomes smaller, the force acting on the motor also becomes smaller.

### • Slip Torque

For set screw type **XGT XGS**, see Aluminum Alloy Coupling under "Slip Torque of Coupling - Set Screw Type" for details.

As in the table below, the clamping types **XGT-C**, **XGT-CS**, **XGS-CS**, and **XGL-C** have different slip torque according to the bore diameter. Take care during selection.

'	Ur													nit : N · m				
Outside Diameter	Bore Diameter (mm)																	
Outside Diameter	3	4	4.5	5	6	6.35	7	8	10	11	12	12.7	14	15	16	17	19	20
15	1	1.3	1.5	1.7	1.9													
19		2.2		2.7	3.1	3.3	3.8											
25				4.3	5	5.5		6.8										
27				3.8	5			6.8										
30								7.5	10	12								
34								8.3	10	10	12		13					
39									13		15	17	17	18	18	23	25	
44											16		19	20	21	23	25	27
56														45			50	61

- These are test values based on the conditions of shaft dimensional allowance: h7, hardness: 34 40 HRC, and screw tightening torque of the values described in XGT-C XGT-C XGS-C XGS-CS XGL-C dimension tables. They are not guaranteed values.
- Slip torque changes with usage conditions. Carry out tests under conditions similar to actual conditions in advance